## UXN14M9P Datasheet

## 14 GHz Divide-by-8 to 511 Programmable Integer Divider

40 pin Quad Flat No Lead (QFN) $6 \times 6 \mathrm{~mm} \mathrm{pkg}, 0.5 \mathrm{~mm}$ pad pitch JEDEC MO-220 Compliant

Marking Information:
UXN14M9P = Device Part Number XXXX = Lot Code

## Product Highlights

- Wide Operating Range: DC - 14 GHz
- Contiguous Divide Ratios: 8 to 511
- Large Output Swings: >1 Vpp/side
- Single-Ended and/or Differential Drive
- Size: 6mm x 6mm
- Parallel Control Lines
- Low SSB Phase Noise:
-147 dBc @ 10 kHz Offset


## Description

The UXN14M9P is a highly programmable integer divider covering all integer divide ratios between 8 and 511. The device features single-ended or differential inputs and outputs. Parallel control inputs are CMOS and LVTTL compatible for ease of system integration. The UXN14M9P is packaged in a 40-pin, $6 \mathrm{~mm} \times 6 \mathrm{~mm}$ leadless plastic surface mount package.

## Pad Metallization

The QFN package pad metallization consists of a 300-800 micro-inch (typical thickness 435 micro-inch or 11.04um) 100\% matte Sn plate. The plating covers a Cu (C194) leadframe. The packages are manufactured with $\mathrm{a}>1 \mathrm{hr} 150 \mathrm{C}$ annealing/heat treating process, and the matte (non-glossy) plating, specifically to mitigate tin whisker growth.

## Application

The UXN14M9P can be used as a general purpose, highly configurable, divider in a variety of high frequency synthesizer applications. Fast switching combined with a wide range of divide ratios make the UXN14M9P an excellent choice for fractional-N and integer-N PLLs. Fractional division may be achieved by applying a sequence to the divider control lines, such as a delta-sigma modulated sequence.

## Key Specifications ( $\mathrm{T}=25^{\circ} \mathrm{C}$ )

Vee $=-3.3 \mathrm{~V}$, lee $=185 \mathrm{~mA}, \mathrm{Zo}=50 \Omega$

| Parameter | Description | Min | Typ | Max |
| :--- | :--- | :---: | :---: | :---: |
| $\mathrm{F}_{\text {in }}(\mathrm{GHz})$ | Input Frequency | $\mathrm{DC}^{*}$ | - | 14 |
| $\mathrm{P}_{\text {in }}(\mathrm{dBm})$ | Input Power | - | 0 | +10 |
| $\mathrm{P}_{\text {out }}(\mathrm{dBm})$ | Output Power | - | +4 | - |
| $\mathrm{P}_{\mathrm{DC}}(\mathrm{W})$ | DC Power Dissipation | - | 1.1 | - |
| $\left.\theta_{\mathrm{jc}}{ }^{( } \mathrm{C} / \mathrm{W}\right)$ | Junction-Case Thermal Resistance | - | 14 | - |

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## UXN14M9P Datasheet

## Frequency Divider Application



Figure 1: Min/Max Single-Ended Input Power Input Sensitivity Window


Figure 3: Static Divide-by-8 Configuration Input Freq $=14 \mathrm{GHz}$


Figure 5: Dynamic Divide-by-8/9 Application Input Freq $=14 \mathrm{GHz}$


Figure 2: Divide-by-8 Output Power, 3rd Harmonic \& Input Feedthru


Figure 4: Static Divide-by-511 Configuration Input Freq $=14 \mathrm{GHz}$


Figure 6: Dynamic Divide-by-16/17 Application Input Freq $=14 \mathrm{GHz}$

## UXN14M9P Datasheet



Figure 7: Functional Block Diagram

## Pin Description

| Port Name | Description | Notes |
| :--- | :--- | :--- |
| INP | Divider Input, Positive Terminal | CML signal levels |
| INN | Divider Input, Negative Terminal | CML signal levels |
| OUTP | Divider Output, Positive Terminal | CML signal levels |
| OUTN | Divider Output, Negative Terminal | CML signal levels |
| P0-P8 | Divider Modulus Control (P8=MSB) | CMOS levels, see Equation 1, defaults to logic 0 |
| VCC | RF \& DC Ground | The paddle is connected to +VCC inside the package |
| VEE | -3.3 V @ 340 mA | Negative Supply Voltage |

## Equation 1

Divider Modulus $=N=P_{0} \cdot 2^{0}+P_{1} \cdot 2^{1}+P_{2} \cdot 2^{2}+\ldots+P_{8} \cdot 2^{8} \quad$ for $8 \leq N \leq 511$

## CMOS Levels for control lines P0-P8

| Logic Level | Minimum | Typical | Maximum |
| :---: | :---: | :---: | :---: |
| 1 (High) | Vcc-1.25V | Vcc-0.8V | Vcc-0.8V |
| 0 (Low) | Vee | Vee | Vee +1.25 V |

Simplified Control Logic Schematic


Figure 8: Simplified Control Logic Schematic

## UXN14M9P Datasheet

## Low Frequency Operation

Low frequency operation is limited by external bypass capacitors and the slew rate of the input clock. The next paragraph shows the calculations for the bypass capacitors. If DC coupled, the device operates down to DC for square-wave inputs. Sine-wave inputs are limited to $\sim 50 \mathrm{MHz}$ due to the 10 dBm max input power limitation.

The values of the coupling capacitors for the high-speed inputs and outputs (I/O's) are determined by the lowest frequency the IC will be operated at.

$$
C \gg \frac{1}{2 \cdot \pi \cdot 50 \Omega \cdot f_{\text {lowest }}}
$$

For example to use the device below 30 kHz , coupling capacitors should be larger than 0.1uF.

## IC Assembly

The device is designed to operate with either single-ended or differential inputs. Figures $1,2 \& 3$ show the IC assembly diagrams for positive and negative supply voltages. In either case the supply should be capacitively bypassed to the ground to provide a good AC ground over the frequency range of interest. The backside of the chip should be connected to a good thermal heat sink.

All RF I/O's are connected to VCC through on-chip termination resistors. This implies that when VCC is not DC grounded (as in the case of positive supply), the RF I/O's should be AC coupled through series capacitors unless the connecting circuit can generate the correct levels through level shifting.

## ESD Sensitivity

Although SiGe IC's have robust ESD sensitivities, preventive ESD measures should be taken while storing, handling, and assembling.

Inputs are more ESD susceptible as they could expose the base of a BJT or the gate of a MOSFET. For this reason, all the inputs are protected with ESD diodes. These inputs have been tested to withstand voltage spikes up to 400 V .

CML Logic Levels for DC Coupling ( $\mathrm{T}=25^{\circ} \mathrm{C}$ )
Assuming $50 \Omega$ Terminations at Inputs and Outputs

| Parameter |  |  | Minimum | Typical | Maximum |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input | Differential | Logic Input $_{\text {high }}$ Logic Input $_{\text {low }}$ | $\begin{gathered} \text { Vcc } \\ \text { Vcc }-0.05 \mathrm{~V} \end{gathered}$ | $\begin{gathered} \mathrm{Vcc} \\ \mathrm{Vcc}-0.3 \mathrm{~V} \end{gathered}$ | Vcc <br> Vcc-1 V |
|  | Single | Logic Input ${ }_{\text {high }}$ Logic Input ${ }_{\text {low }}$ | $\begin{aligned} & V c c+0.05 V \\ & V c c-0.05 V \end{aligned}$ | $\begin{aligned} & V c c+0.3 V \\ & V c c-0.3 V \end{aligned}$ | $\begin{aligned} & \mathrm{Vcc}+1 \mathrm{~V} \\ & \mathrm{Vcc}-1 \mathrm{~V} \end{aligned}$ |
| Output | Differential \& Single | Logic Output $_{\text {high }}$ <br> Logic Output $_{\text {ow }}$ | $\begin{aligned} & \mathrm{Vcc}-0.9 \mathrm{~V} \\ & \mathrm{Vcc}-1.1 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & V c c-0.6 V \\ & V c c-1.6 V \end{aligned}$ | $\begin{aligned} & \mathrm{Vcc}-0.5 \mathrm{~V} \\ & \mathrm{Vcc}-1.7 \mathrm{~V} \end{aligned}$ | Specifications subject to change without notice. © 2012 Centellax, Inc. 18 Dec 2012. SmD-00020 rev D.

## UXN14M9P Datasheet

## Differential Versus Single-Ended

The UXN14M9P is fully differential to maximize signal-to-noise ratios for high-speed operation. All high speed inputs and outputs are terminated to Vcc with on-chip resistors (refer to functional block diagram for specific resistor values). The maximum DC voltage on any terminal must be limited to Vcc +/- 1 V to prevent damaging the termination resistors with excessive current. Regardless of bias conditions, the following equation should be satisfied when driving the inputs differentially:

$$
\mathrm{V}_{\mathrm{CC}}-1<\mathrm{V}_{\mathrm{AC}} / 4+\mathrm{V}_{\mathrm{DC}}<\mathrm{V}_{\mathrm{CC}}+1
$$

where VAC is the input signal p-p voltage and VDC is common-mode voltage.
The outputs require a DC return path capable of handling $\sim 30 \mathrm{~mA}$ per side. If DC coupling is employed, the DC resistance of the receiving circuits should be 50 ohms to Vcc . If $A C$ coupling is used, a bias tee circuit should be used such as shown below. The discrete R/L/C elements should be resonance free up to the maximum frequency of operation for broadband applications.


In addition to the maximum input signal levels, single-ended operation imposes additional restrictions: the average DC value of the waveform at IC should be equal to Vcc for single-ended operation. In practice, this is easily achieved with a single capacitor on the input acting as a DC block. The value of the capacitor should be large enough to pass the lowest frequencies of interest.

Note that a potential oscillation mechanism exists if both inputs are static and have identical DC voltages; a small DC offset on either input is sufficient to prevent possible oscillations. Connecting a 10k ohm resistor between the unused input and Vee should provide sufficient offset to prevent oscillation.

## UXN14M9P Datasheet

## Negative Supply (DC Coupling)



Figure 9: DC Coupling Negative Supply

## Negative Supply (AC Coupling)



Figure 10: AC Coupling Negative Supply

## UXN14M9P Datasheet

## Positive Supply (AC Coupling)

(Note that the metalized backside of the QFN package - the paddle - is internally connected to Vcc, therefore will be at +3.3 V potential for the positive supply case. The paddle needs to be soldered to a pad on the pcb to provide heatsinking for the divider; special attention to the pcb design is required to isolate the pcb pad from ground.)


Figure 11: AC Coupling Positive Supply

## UXN14M9P Datasheet

## Application Notes

## Duty Cycle

The UXN14M9P output duty cycle varies between $25 \%$ and $64 \%$ as a function of the divide ratio. For divide ratios between 16 and 511 , the pulse width remains constant in each octave band (e.g. between 128 and 255 ), and gives a duty cycle of $50 \%$ for powers of 2 . Thus, the duty cycle is bounded between 25 and $50 \%$ for divide ratios between 16 and 511 . For divide ratios between 8 and 15 , the pulse width does not stay fixed, but varies with the divide ratio. The duty cycle ranges from $33 \%$ to $64 \%$ for these divide ratios. The table shown below gives pulse width and other necessary information for computing the duty cycle, given the divide ratio. The equation provided allows calculation of the duty cycle based on the information supplied by the table. A chart below summarizes the duty cycles for all possible divide ratios.

$$
\text { Duty Cycle (\%) }=\frac{\text { Pulse Width }}{\text { Divide Ratio }} \times 100 \%
$$



Table: Duty Cycle Summary

| Divide Ratio | Pulse Width (Input <br> Cycles) | Duty Cycle (\%) |
| :---: | :---: | :---: |
| 8 | 4 | 50 |
| 9 | 5 | 55.6 |
| 10 | 6 | 60 |
| 11 | 7 | 63.6 |
| 12 | 4 | 33.3 |
| 13 | 5 | 38.5 |
| 14 | 6 | 42.9 |
| 15 | 7 | 46.7 |
| $16-31$ | 8 | $50-25$ |
| $32-63$ | 16 | $50-25$ |
| $64-127$ | 32 | $50-25$ |
| $128-255$ | 64 | $50-25$ |
| $256-511$ | 128 | $50-25$ |

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## UXN14M9P Datasheet

## Dynamic Programming Requirements

The UXN14M9P achieves contiguous divisions by retiming the input controls for the divide ratio each output cycle. This feature is fitting for applications where the divide ratio requires quick programmability, such as in fractional- N synthesizers. A representative diagram of how the part might be used in such an application is shown below. In this setup the divider output is used to clock (or update) the control circuitry. The polarity of the output edge is chosen by the user depending on the relative timing of the control transistions to the output edge.

T setup as defined in the timing diagram, is given by the following formula:

$$
\mathrm{T} \text { setup }=4 * \text { Tinput }+0.7 \mathrm{nsec}
$$

where Tinput=input period. Notice that for $\mathrm{N}=8$ and input frequencies above 6 GHz (Tinput<165 psec), T setup exceeds the output period. Thus, an appropriate latency must be introduced to achieve proper updating. Thold shows the region to avoid updating of the control signal.

Assuming that the divide controls are updated within one output cycle of the output rising edge, a chart is provided showing the recommended minimum divide ratios plotted against input frequency. This means for a given input frequency, all divide ratios above the minimum recommended divide ratio will achieve smooth divisions, whereas any divide ratio below the minimum may produce momentary errors. These values are a general guideline and may vary depending on the exact situation in which it is used.


## UXN14M9P Datasheet

## UXN14M9P Physical Characteristics



| Pkg Size: | $6.00 \times 6.00 \mathrm{~mm}$ |
| :--- | :--- |
| Pkg Size Tolerance: | $+/-0.25 \mathrm{~mm}$ |
| Pkg Thickness: | $0.9+/-0.1 \mathrm{~mm}$ |
| Pad Dimensions: | $0.23 \times 0.4 \mathrm{~mm}$ |
| Center Paddle: | $4.20 \times 4.20 \mathrm{~mm}$ |
| JEDEC Designator: | MO-220 |

## TOP VIEW

11121314151617181920

## UXM14M9P Pin Definition

| Pin Function |  | Operational Notes |
| :---: | :---: | :---: |
| 1,6,11,17-20,23-29,padddle (Vcc) | RF and DC Ground | 0 V |
| 2,3,7-10,12-14,21,22,30,40 (Vee) | Negative Supply Voltage | Nominally -3.3 V |
| 4 (INN) | Divider Input | Negative Terminal of differential input |
| 5 (INP) | Divider Input | Positive Terminal of differential input |
| 15 (OUTP) | Divider Output | Positive Terminal of differential output |
| 16 (OUTN) | Divider Output | Negative Terminal of differential output |
| 31 (P8) | Divide Modulus Control (MSB) | Defaults to logic 0, connect to Vcc-0.8V for logic 1 |
| 32 (P7) | Divide Modulus Control | Defaults to logic 0, connect to Vcc-0.8V for logic 1 |
| 33 (P6) | Divide Modulus Control | Defaults to logic 0, connect to Vcc-0.8V for logic 1 |
| 34 (P5) | Divide Modulus Control | Defaults to logic 0, connect to Vcc-0.8V for logic 1 |
| 35 (P4) | Divide Modulus Control | Defaults to logic 0, connect to Vcc-0.8V for logic 1 |
| 36 (P3) | Divide Modulus Control | Defaults to logic 0, connect to Vcc-0.8V for logic 1 |
| 37 (P2) | Divide Modulus Control | Defaults to logic 0, connect to Vcc-0.8V for logic 1 |
| 38 (P1) | Divide Modulus Control | Defaults to logic 0, connect to Vcc-0.8V for logic 1 |
| 39 (P0) | Divide Modulus Control (LSB) | Defaults to logic 0 , connect to Vcc-0.8V for logic 1 |
| Paddle (Backside of Package) | Vcc | Should be tied to VCC |

## Absolute Maximum Ratings

| Parameter | Value | Unit |
| :--- | :--- | :--- |
| Supply Voltage (VCC-VEE) | 4.0 | V |
| RF Input Power (INP, INN) | +10 | dBm |
| Operating Temperature | -40 to 85 | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature | -85 to 125 | ${ }^{\circ} \mathrm{C}$ |
| Junction Temperature | 125 | ${ }^{\circ} \mathrm{C}$ |

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[^0]:    *Low frequency limit dependent on input edge speed

